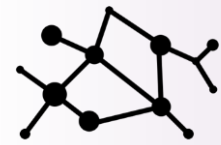




UC San Diego

JACOBS SCHOOL OF ENGINEERING  
Electrical and Computer Engineering



**WCSNG**

Wireless Communications  
Sensing and Networking

# mMobile: A Compact and Real-Time Millimeter-wave Experiment Framework with True Mobility Capabilities



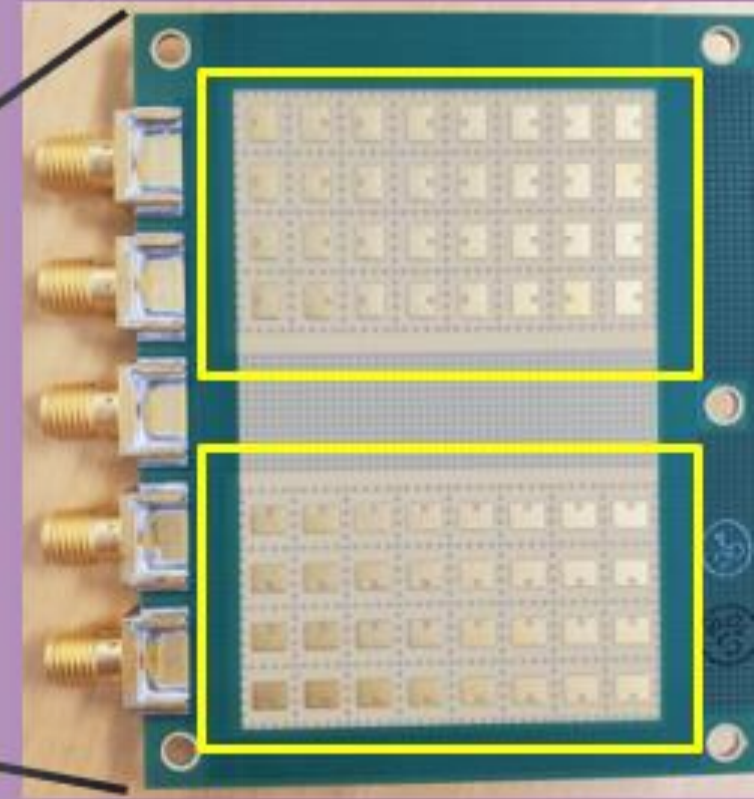
Ish Jain



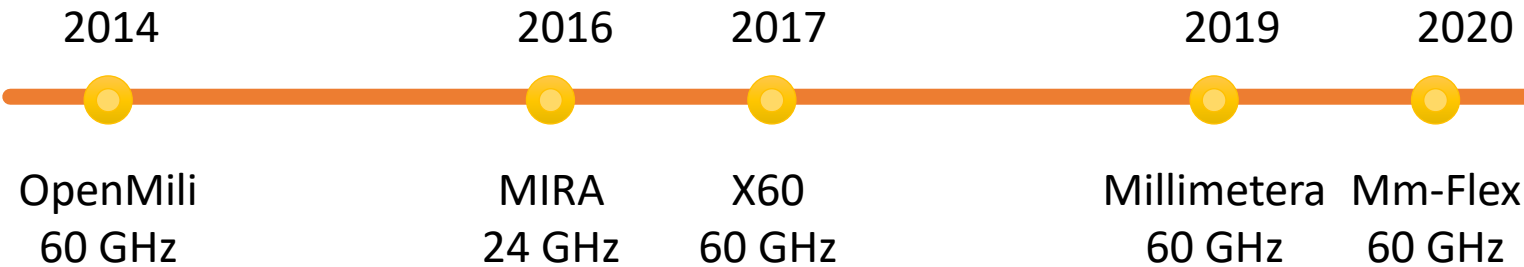
Raghav Subbaraman



Dinesh Bharadia



# Testbeds – Predominantly 60 GHz



<b>60 GHz mmWave</b>	<b>28 GHz mmWave</b>
<b>Limited adoption</b>	<b>Deployments Ramping up</b>
<b>IEEE 802.11ad</b>	<b>3GPP 5G-NR</b>
<b>High attenuation (O2 absorption)</b>	<b>Better propagation</b>

**Need testbeds at 28 GHz to keep up with current trends**

# mMobile 28 GHz Testbed

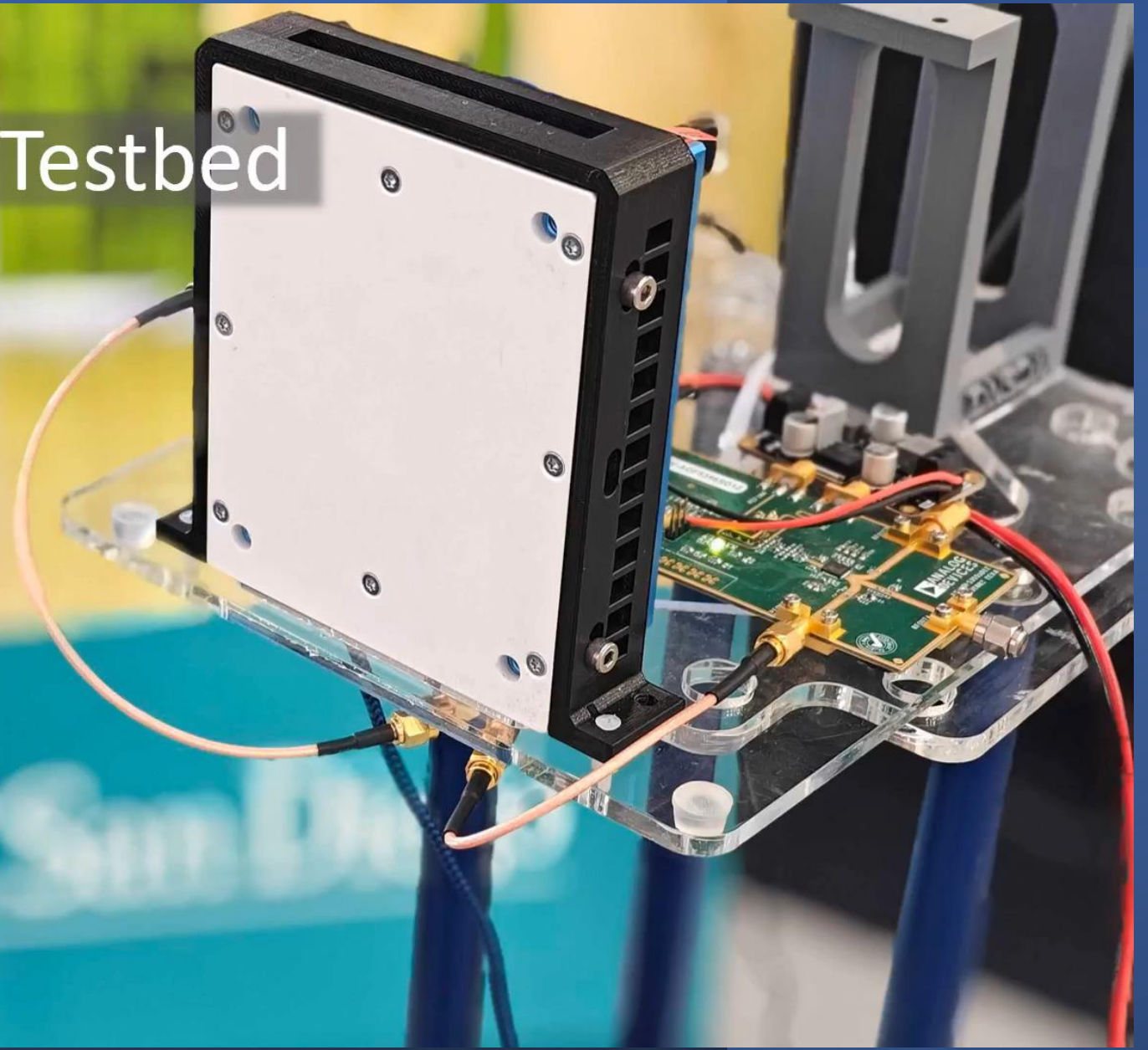


## Features

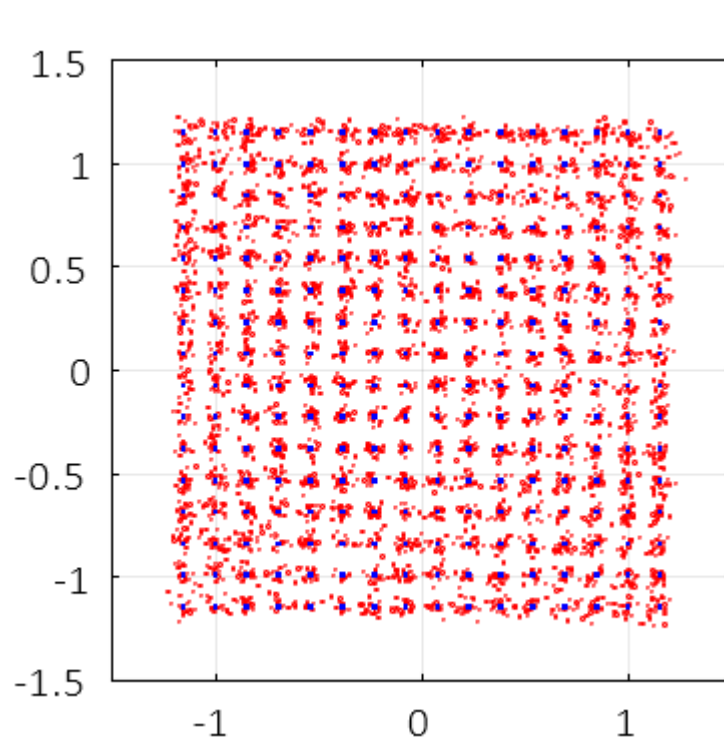
- **Compact** hand-held setup
- **Fast scan**:  $2\mu\text{s}$ /beam with FPGA
- **Large** 1024 size codebook
- **Precise** phase and gain control
- **5G NR** ready



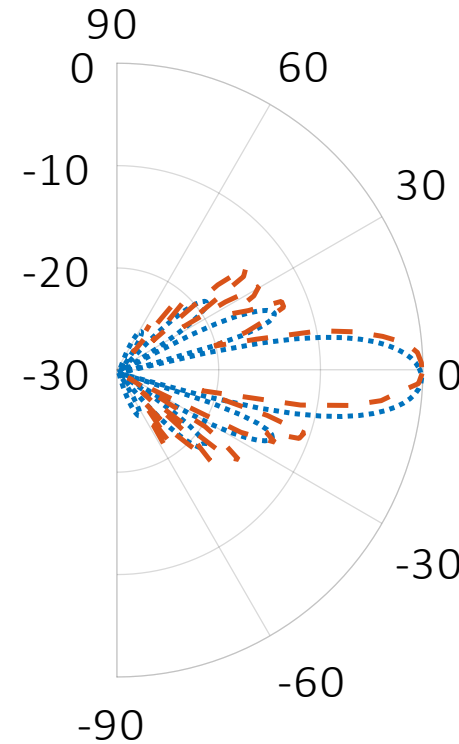
# mMobile 28 GHz Testbed



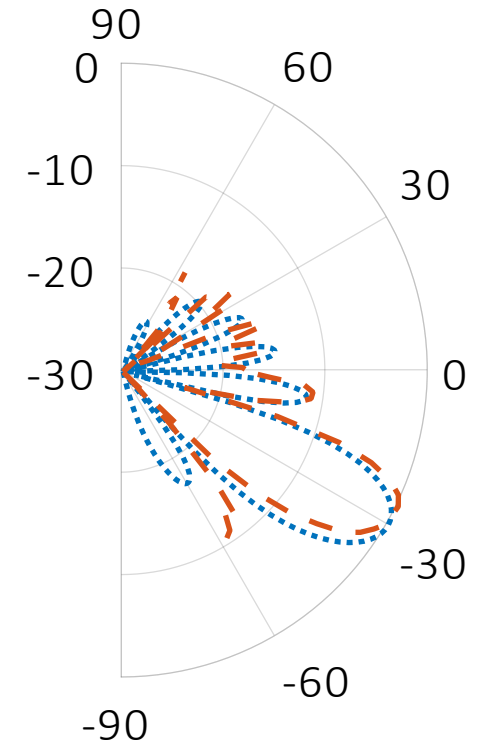
# 256 QAM modulation and perfect beam patterns



· Tx · Rx

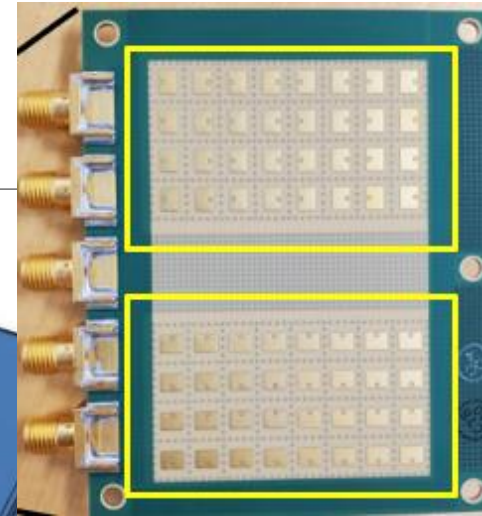
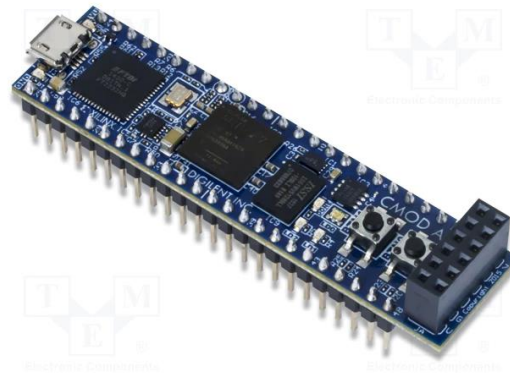


..... Theory - - - Measured

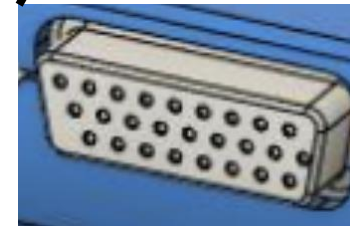


# Fast Programming phased array

- Goal – Control the beam pattern of the phased array.
  - How? – Registers in the phased array contain the phase and gain values corresponding to a beam pattern.
- Objective – Program the registers with the required phase and gain values.
  - How? – Registers can be programmed using microcontrollers through **SPI** interface.



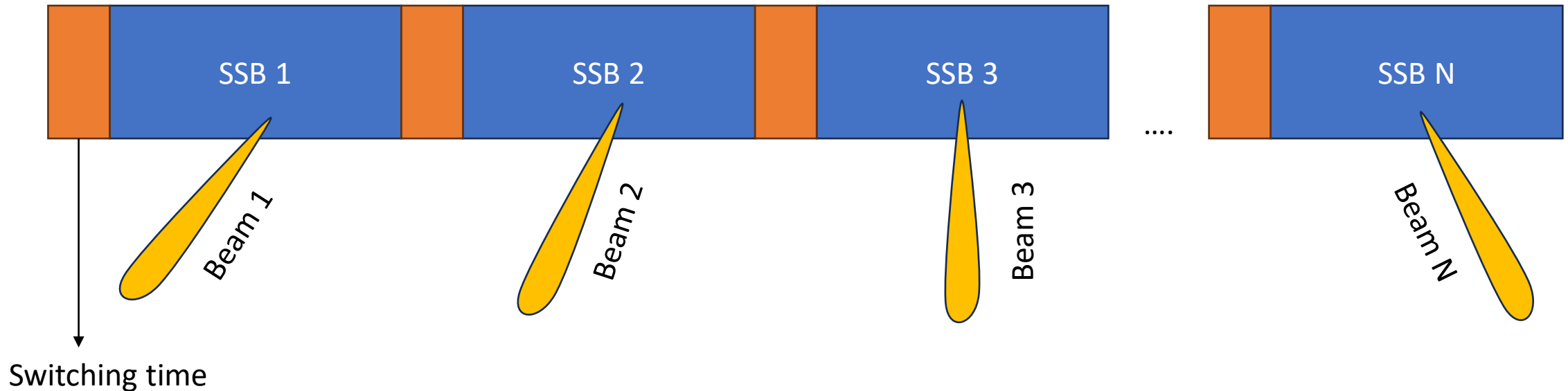
Front end



# Support for 5G NR waveforms

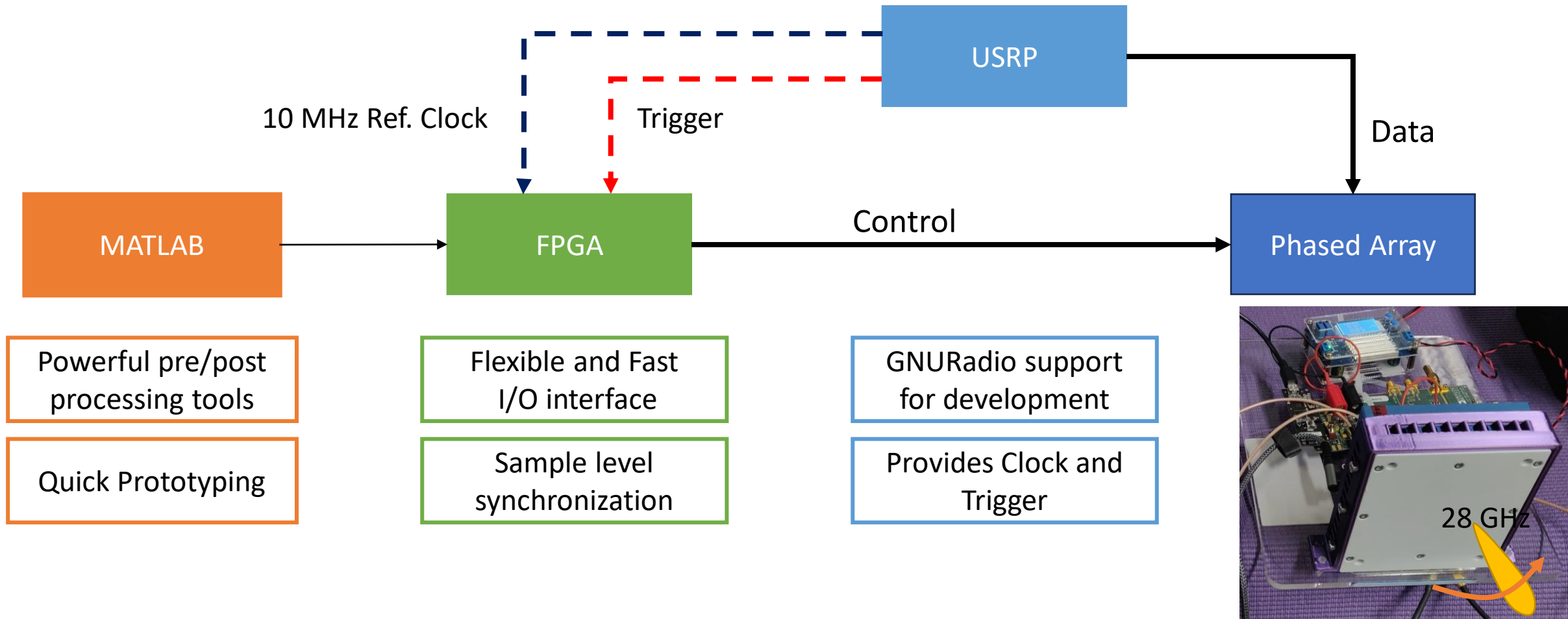
5G NR waveform support:

- 5G NR waveform with SSB length of 12.5us is taken.
- Next beam is switched within 3us.





# USRP – FPGA interface for synchronized beam scan

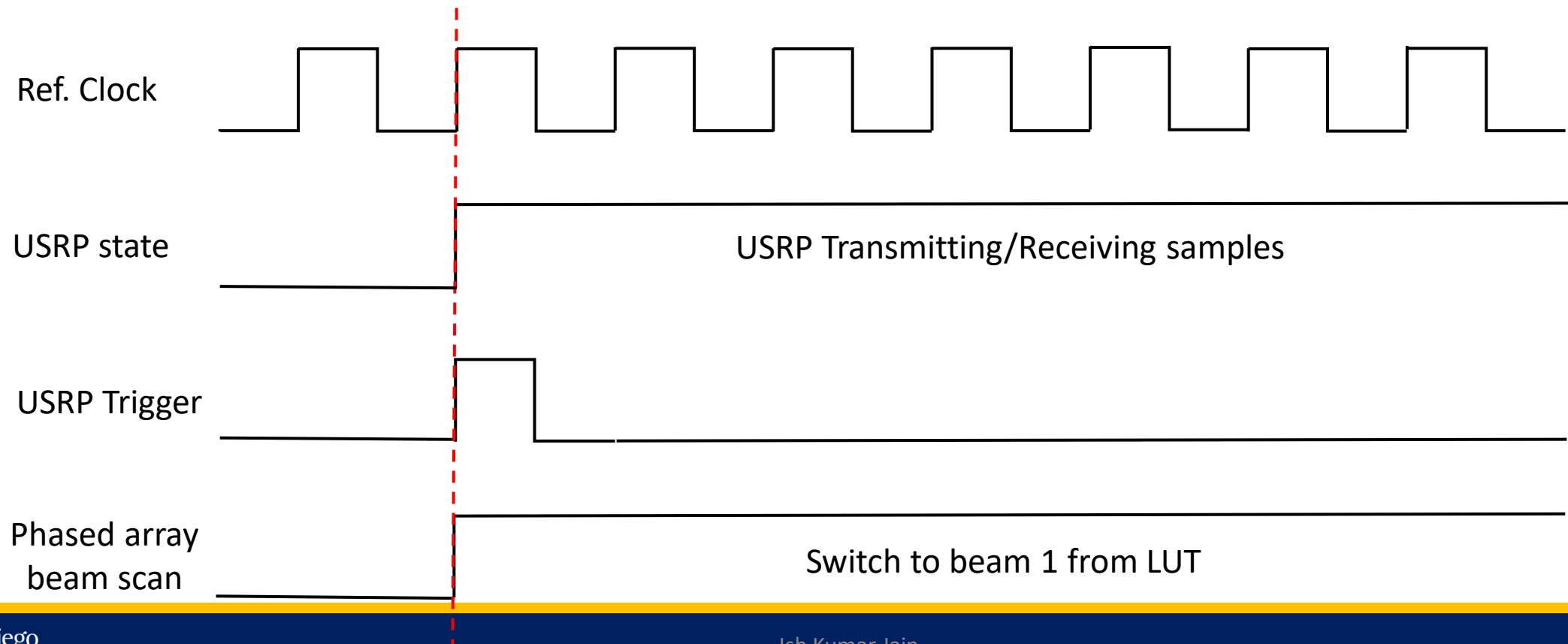




# How we achieve synchronization?

## Synchronization with USRP:

- Both USRP and FPGA have the same reference clock
- Trigger from USRP upon beginning of transmission or reception
- Enables sample level synchronization between USRP and Phased Array.



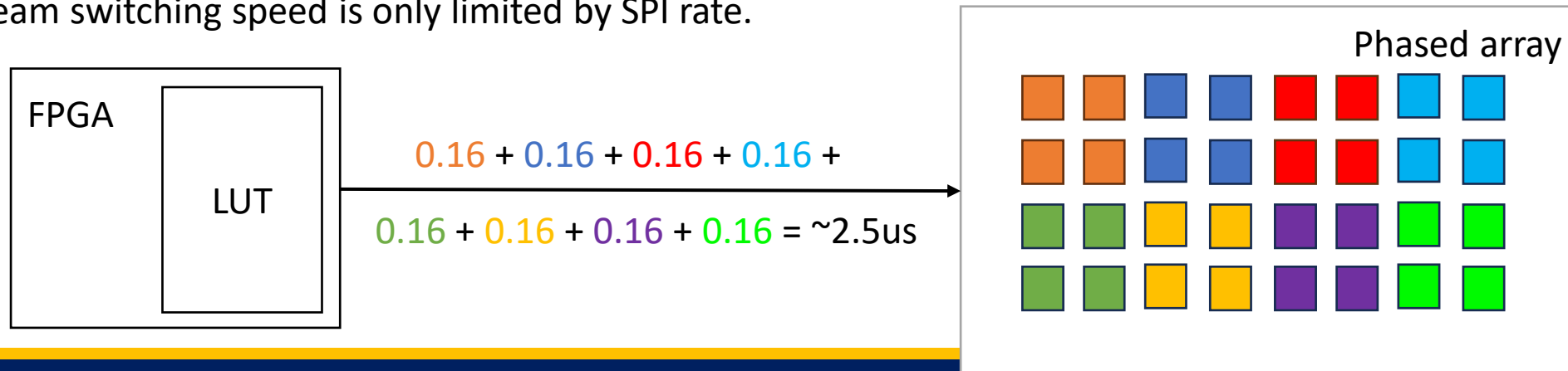
# How we get fast Beam switching to 3 us?

Fast beam switching:

- SPI operates up to 50MHz = 50 Mbps
- One SPI byte level transfer =  $1/50 * 8 = 0.02 * 8 = 0.16\mu\text{s}$
- Loading beam configuration to each beamformer chip requires a 2-byte SPI command
- For a 32-element array, with one beamformer chip for every 4 elements, beam switching can be done within  $2 \text{ bytes} * 0.16\mu\text{s} / \text{byte} * 32 / 4 = \sim 2.5\mu\text{s}$ .
- Thus, beam switching can be done under 3us.

LUT:

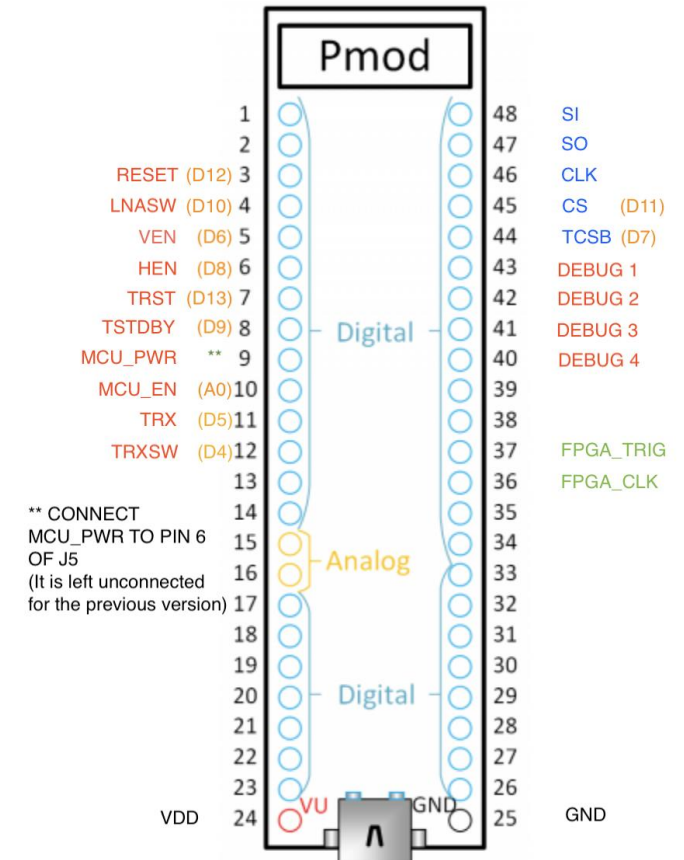
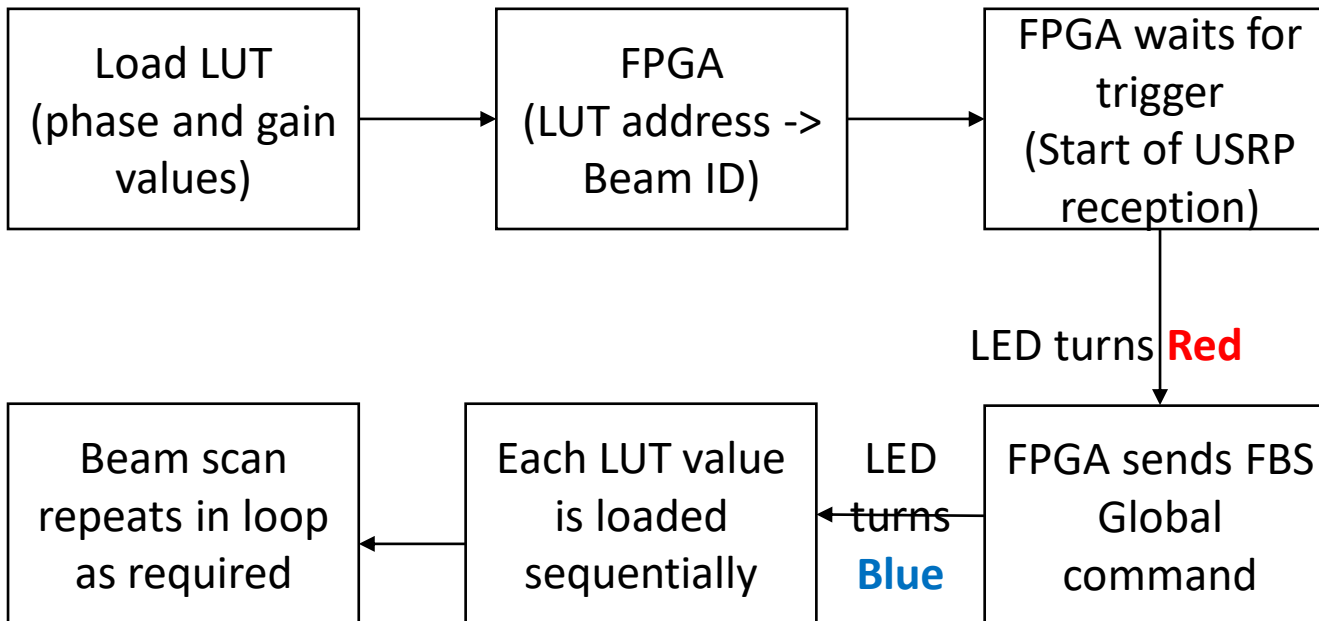
- LUTs are used to store the beam configurations within the FPGA.
- Mitigates the need to calculate beam configuration values every time before sending SPI command.
- Thus, beam switching speed is only limited by SPI rate.



# FPGA Programming

- Synchronized with USRP clock, either by using the USRP clock as reference or feeding a common reference clock for both FPGA and USRP.
- Receives trigger from USRP, indicating the start of reception of signal.
- Receives commands from MATLAB through UART.
- Decode and extract the SPI command embedded within the UART message, according to the mapping shown in previous slide.

## Fast Beam Scan:



# FPGA Programming details

## Load LUT:

- The LUT address is calculated in the FPGA and appended into the SPI message extracted from UART (data[1] and data[2]).
- The mapping with Beam ID is stored (trackerLUT).

```
int chipAddress = (data[0] & 60) >> 2;
int LUTAddress = floor(trackerLUT[chipAddress] / 4);
data[1] = LUTAddress >> 3;
data[2] = (data[2] | (LUTAddress << 5));
trackerLUT[chipAddress] = trackerLUT[chipAddress] + 1;
```

## FPGA waits for trigger:

```
do{FreezeSignal =XGpio_DiscreteRead(&Gpio, GPIO_CHANNEL); // Continuously reading the GPIO pins
}while((FreezeSignal&1)!=0);
```

## Fast Beam Scan:

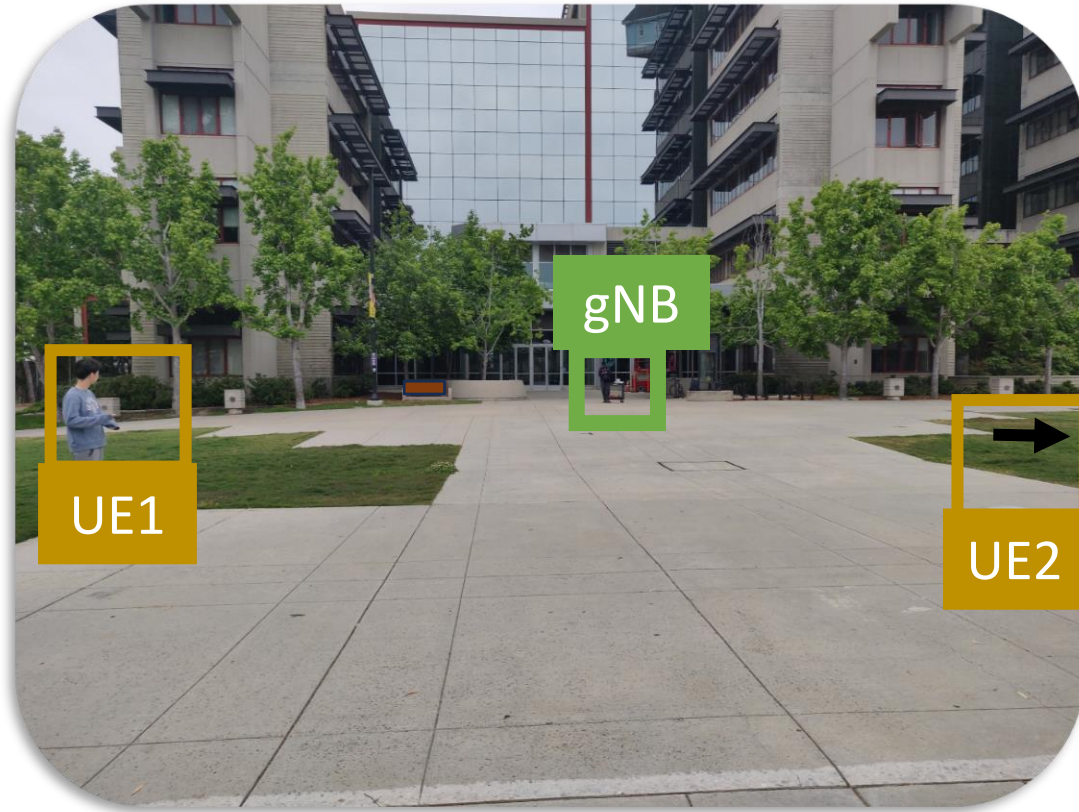
- Preload the SPI messages in array to avoid calculation during beam scan (loadedData).
- Send the preloaded SPI messages sequentially.
- Wait in the beam configuration for the switch period interval.
- Repeat the beam scan for the number of codebook repetitions (numCBrep).

```
for (int addressLUT = 0; addressLUT < CBSize; addressLUT++){
    loadedData[addressLUT * 2] = (1 << 7) | (pol << 5) | (mode << 4) | (addressLUT >> 7);
    loadedData[addressLUT * 2 + 1] = (addressLUT << 1) | latchEN;
}

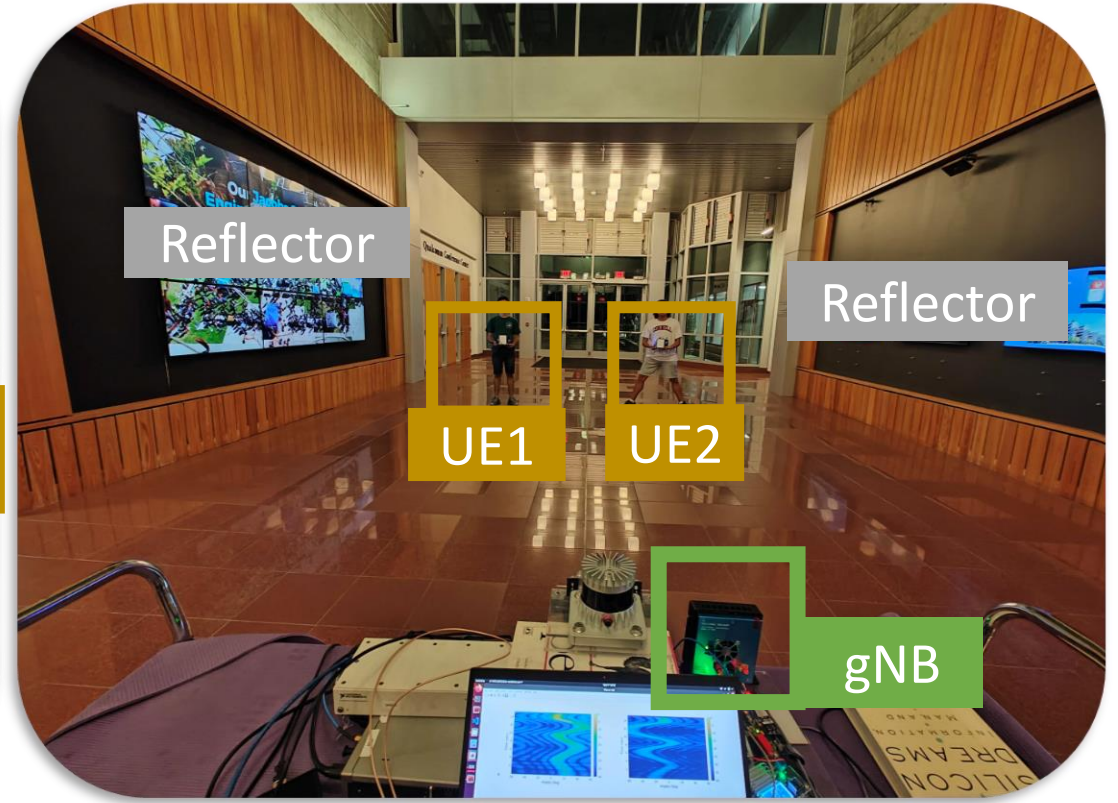
for(int rep = 0; rep < numCBrep; rep++){
    for (int addressLUT = 0; addressLUT < CBSize; addressLUT++){
        XSpi_Transfer(SpiInstancePtr, &loadedData[addressLUT * 2], ret, 2);
        do{ TimerValue=XTmrCtr_GetTimerCounterReg(TMRCTR_BASEADDR, TIMER_COUNTER_0);
        }while(TimerValue>=100);
    }
}
```



# Experimental scenario

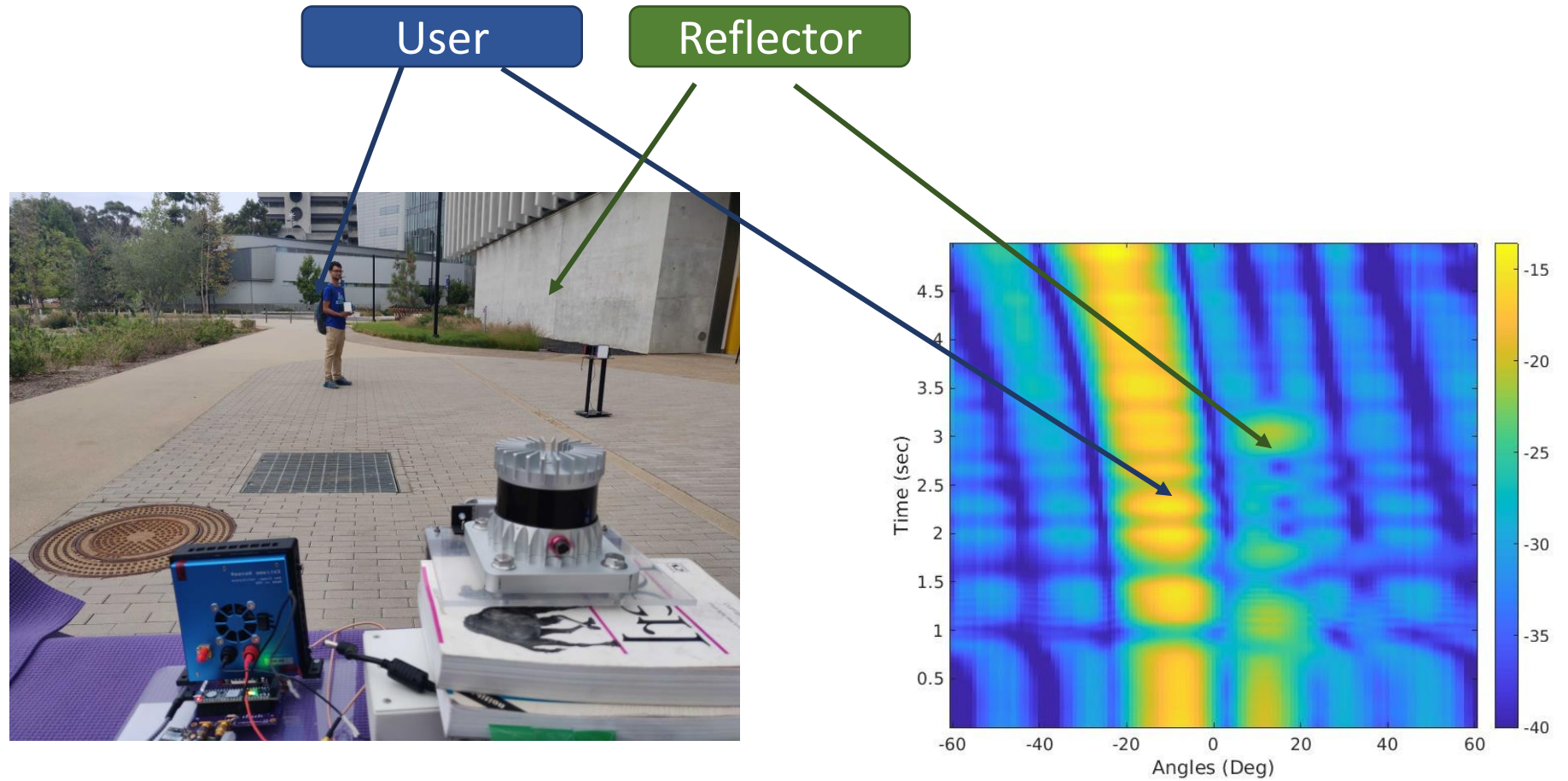


Outdoor Scenario



Indoor Scenario

# Users and Reflector measurement



Experiment Scenario

Beam scan measurement

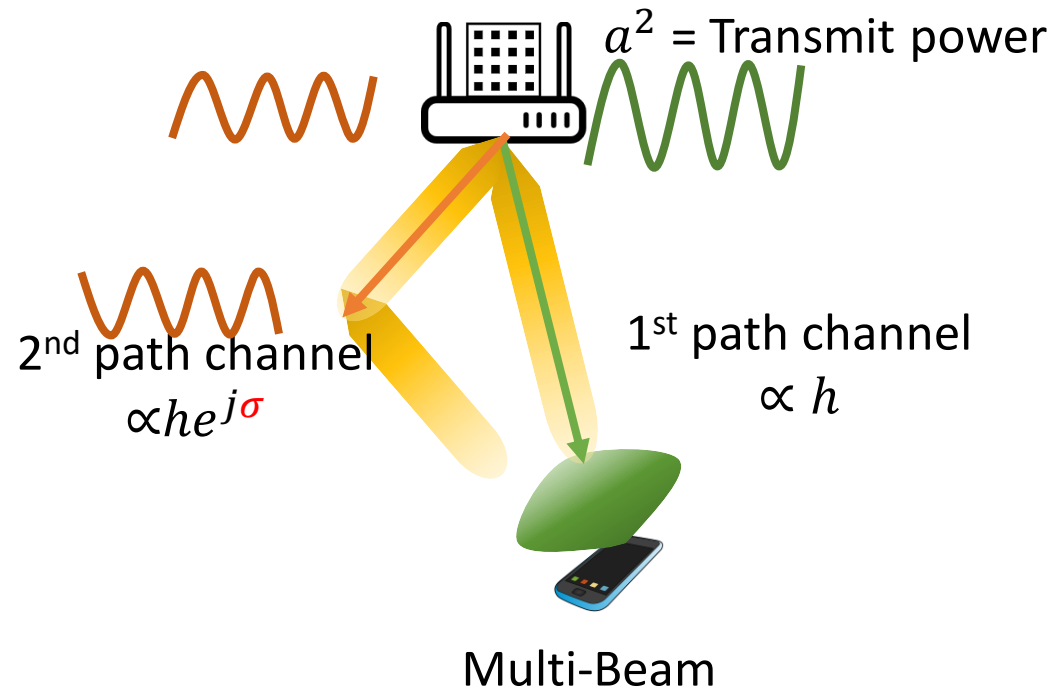
# mmReliable: Two beams are better than one



Destructive Multi-Beam



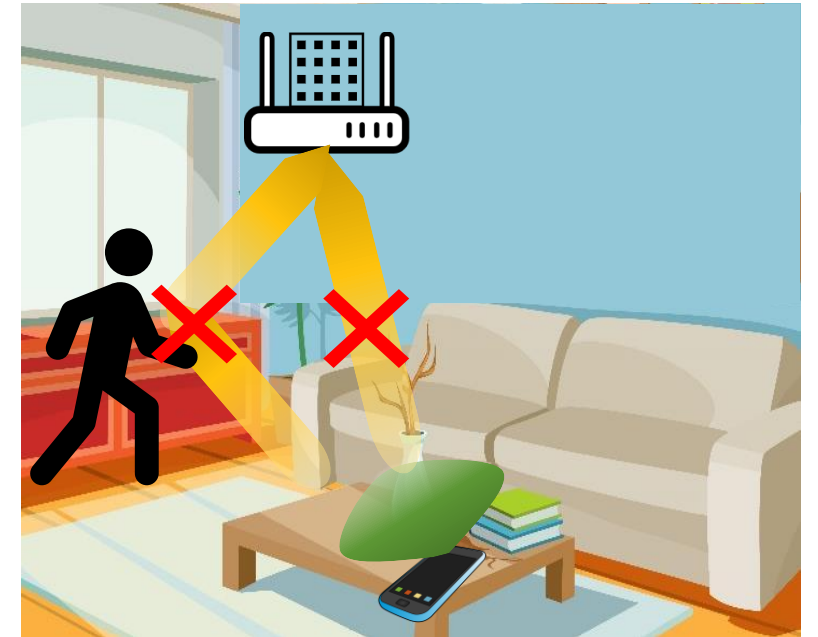
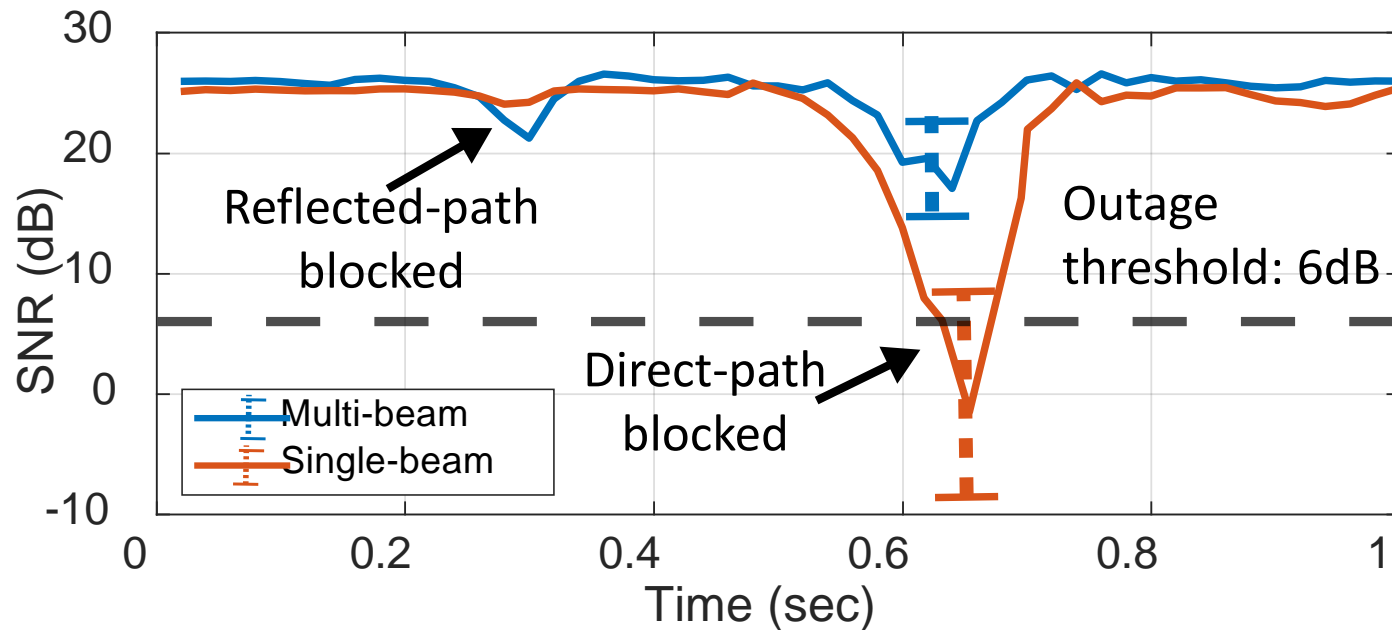
Constructive Multi-Beam



CMB SNR $\propto  \sqrt{2}ah ^2 = 2a^2  h ^2$	Single-beam SNR $\propto a^2  h ^2$
--------------------------------------------------	----------------------------------------

Constructive multi-beams (CMB) requires **phase and power control** to achieve 2x better SNR and higher throughput than single beam

# Constructive multi-beams are resilient to blockages



Multi-beam maintain high throughput despite occasional blockages





## Publications

[mmReliable] Two beams are better than one: Towards reliable and high throughput mmWave links, ACM SIGCOMM 2021

mmFlexible: Towards Flexible Directional Multiplexing for Multi-user mmwave Networks, IEEE INFOCOM 2023

mMobile: Building a mmwave testbed to evaluate and address mobility, ACM mmNets workshop 2020

mmSpoof: Resilient Spoofing of Automotive Millimeter-wave Radars using Reflect Array, IEEE S&P 2023

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